

DYNAMIQUE DE LA ROTATION

PGC-10

LE CENTRE DE MASSE - RAPPEL

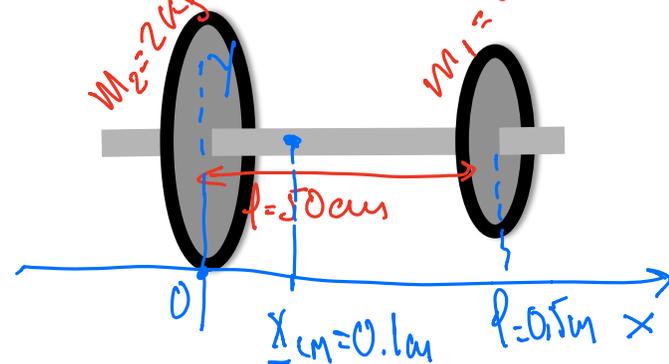
Un haltère se compose d'un disque de 500 gr d'une coté et d'un disque de 2 kg de l'autre coté. On considère la barre qui les connecte sans masse et le longueur 50 cm. Calculer le centre de masse.

$$x_{CM} = \frac{\sum_i F_i x_i}{\sum F_i} \quad F = mg$$

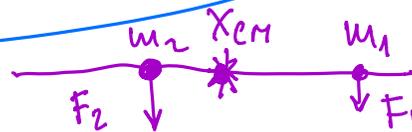
$$x_{CM} = \frac{\sum_i m_i x_i}{\sum m_i}$$

$$x_{CM} = \frac{m_1 r_1 + m_2 r_2}{m_1 + m_2} = \frac{m_2 \cdot 0 + m_1 \cdot l}{m_1 + m_2} \Rightarrow$$

$$\Rightarrow x_{CM} = 0.1 \text{ m}$$



$$\sum T_{CM} = 0$$

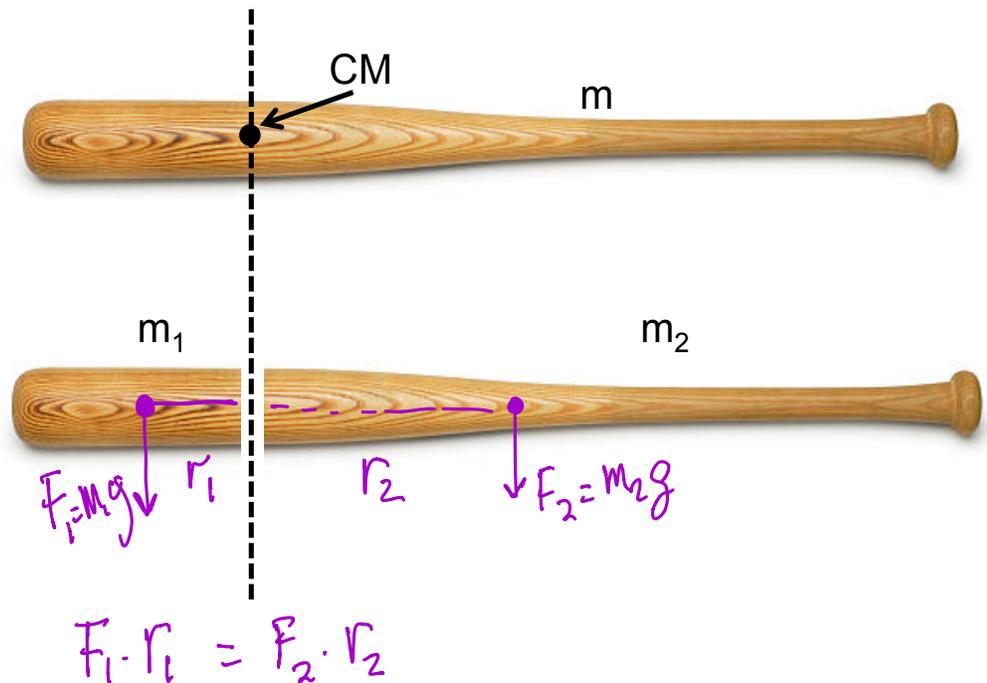


LE CENTRE DE MASSE - QUESTION

(a) $m_1 > m_2$

(b) $m_1 = m_2$

(c) $m_1 < m_2$



DYNAMIQUE DE ROTATION - INTRO

Q rectiligne \Leftrightarrow F masse
"Resistance" $F = ma$

Q angulaire \Leftrightarrow T masse
moment
d'inertie $T = I \cdot a_{ang.}$

MOMENT D'INERTIE

$$T_o = r F = r \cdot m \cdot a_t \quad \left. \begin{array}{l} a_t = r \alpha_{ang} \\ F = m a \end{array} \right\} \Rightarrow T_o = m \cdot r^2 \alpha_{ang}$$

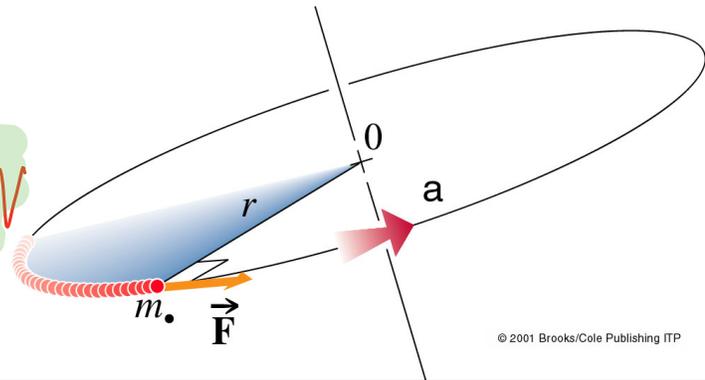


$$T_o = I \cdot \alpha_{ang}$$

$$T_o^{Tot} = \sum T_o = \sum (m_i r_i^2) \alpha_{ang}$$

$$I_o = \sum m_i r_i^2$$

$$dm \quad I = \int r^2 dm \quad \left. \begin{array}{l} dm = \rho dV \end{array} \right\} \Rightarrow I = \int r^2 \rho dV$$



MOMENT D'INERTIE DES CORPS SIMPLES

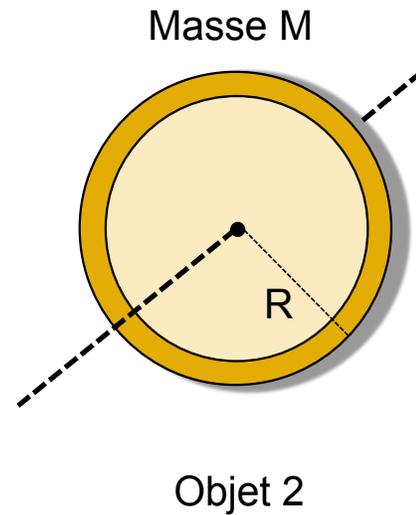
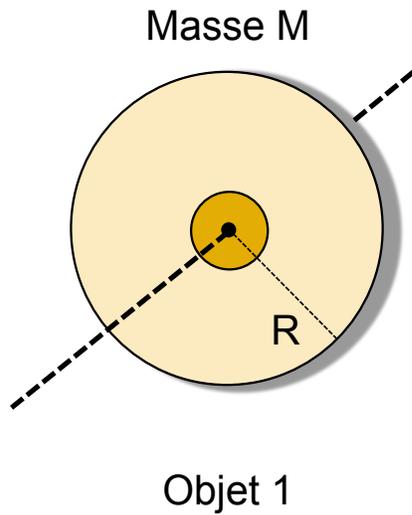
TABLE 12.2 Moments of inertia of objects with uniform density

Object and axis	Picture	I	Object and axis	Picture	I
Thin rod, about center		$\frac{1}{12}ML^2$	Cylinder or disk, about center		$\frac{1}{2}MR^2$
Thin rod, about end		$\frac{1}{3}ML^2$	Cylindrical hoop, about center		MR^2
Plane or slab, about center		$\frac{1}{12}Ma^2$	Solid sphere, about diameter		$\frac{2}{5}MR^2$
Plane or slab, about edge		$\frac{1}{3}Ma^2$	Spherical shell, about diameter		$\frac{2}{3}MR^2$

Handwritten notes in red:

- $I = mr^2$ (with an arrow pointing from the center of mass of the rod to the end)
- $I = M(2r)^2 = 4mr^2$ (with an arrow pointing from the end of the rod to the other end)

MOMENT D'INERTIE



(a) $I_1 > I_2$

(b) $I_1 = I_2$

(c) $I_1 < I_2$

EXEMPLE

Une masse $m = 10.0 \text{ kg}$ est suspendue à une corde enroulée autour d'un cylindre de rayon $R = 10.0 \text{ cm}$ et de masse $M_c = 2.00 \text{ kg}$. Une fois lâché, le cylindre est libre de tourner autour de son axe. Déterminez la tension de la corde, et les accélérations du cylindre et de la masse.



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$$\sum \tau_o = r \cdot F_T \cdot R = I \alpha_{\text{ang}} \Rightarrow F_T = \frac{I \alpha_{\text{ang}}}{R}$$

$$\sum F = m a = m R \cdot \alpha_{\text{ang}}$$

$$m g - F_T = m \cdot R \cdot \alpha_{\text{ang}} \Rightarrow m g - \frac{I \cdot \alpha_{\text{ang}}}{R} = m R \alpha_{\text{ang}} \Rightarrow f_g \downarrow$$

$$\Rightarrow \alpha_{\text{ang}} = \frac{m g}{I/R + m R} \left\{ \Rightarrow \alpha_{\text{ang}} = \frac{m g}{\frac{1}{2} M_c R + m R} = \dots = 89.2 \text{ rad/s}^2 \right.$$

$$I = \frac{1}{2} M_c R^2$$

$$a = R \cdot \alpha_{\text{ang}} = 8.92 \text{ m/s}^2 < g$$

EXAMPLE

$$\vec{L} = \alpha_{\text{ang}} \cdot \vec{I}$$

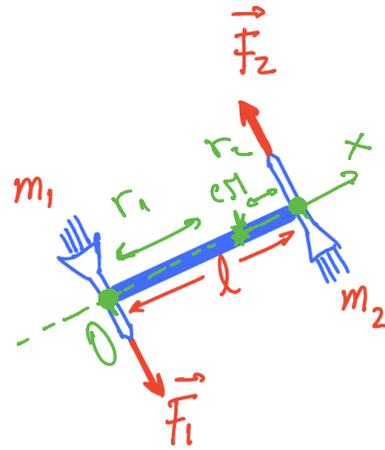
$$X_{\text{CM}} = \frac{m_1 \cdot X_1 + m_2 \cdot X_2}{m_1 + m_2} = 60 \text{ m}$$

$$I = m_1 r_1^2 + m_2 r_2^2 = 540.000.000 \text{ kg m}^2$$

$$\vec{L} = \vec{F}_1 \cdot r_1 + \vec{F}_2 \cdot r_2 = 4.500.000 \text{ Nm}$$

$$\alpha_{\text{ang}} = 0.00833 \text{ rad/s}^2$$

$$\omega = \alpha_{\text{ang}} \Delta t \Rightarrow \omega = 0.25 \text{ rad/s}$$



$$m_1 = 100.000 \text{ kg}$$

$$m_2 = 200.000 \text{ kg}$$

$$l = 90 \text{ m}$$

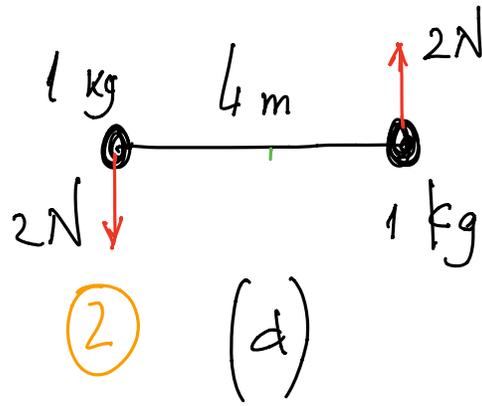
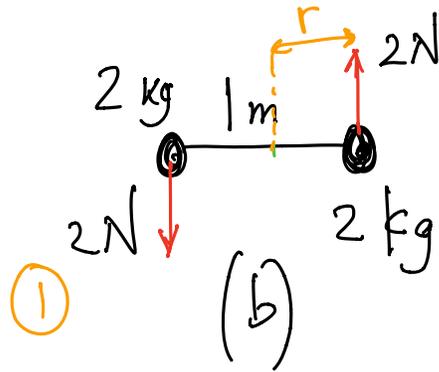
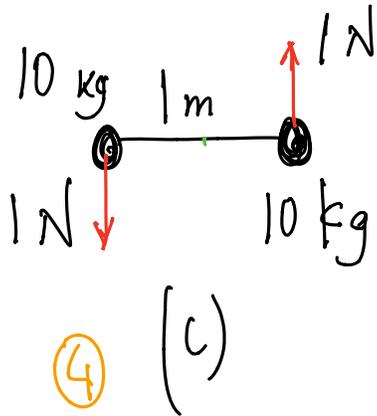
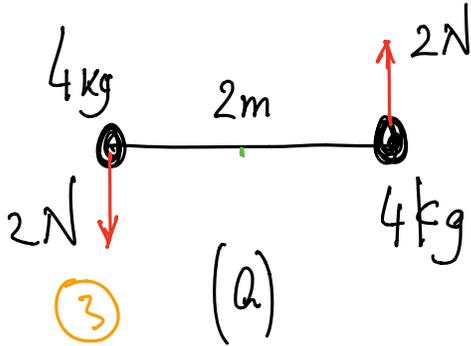
$$F_1 = F_2 = 50.000 \text{ N}$$

$$\omega \text{ at } \Delta t = 30 \text{ s?}$$

$$r_1 = 60 \text{ m}$$

$$r_2 = 30 \text{ m}$$

EXAMPLE



$$\tau = I a_{\text{ang}}$$

Di a_{ang} max?

$$a_{\text{ang}} = \frac{\tau}{I}$$

$$I = 2mr^2$$

$$I \propto mr^2$$

$$\tau \propto Fr$$

$$a_{\text{ang}} \propto \frac{Fr}{mr^2} = \frac{F}{mr}$$

MOMENT CINÉTIQUE

Eq. rotat. $\vec{F} : \vec{\tau}$
 $\vec{p} : \vec{L}$

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{L} = \vec{r} \times \vec{p} \Rightarrow \vec{L} = m \vec{r} \times \vec{v}$$

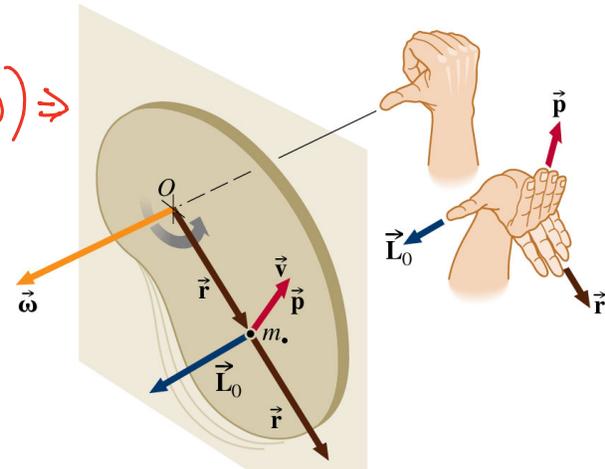
$$\vec{p} = m \vec{v} \quad L = \int (r m v) = \int (r m r \omega) \Rightarrow$$

$$\Rightarrow L = \int m r^2 \omega \rightsquigarrow L = I \omega$$

moment cinétique

$$\vec{L} = I \vec{\omega}$$

$$\vec{p} = m \vec{v}$$



CONSERVATION DU MOMENT CINÉTIQUE

$$\vec{\tau} = I \cdot \vec{\alpha}_{\text{ang}} = I \cdot \frac{\Delta \vec{\omega}}{\Delta t} \quad \left. \begin{array}{l} \Delta \vec{L} = I \Delta \vec{\omega} \Rightarrow \Delta \vec{\omega} = \frac{\Delta \vec{L}}{I} \\ \Rightarrow \vec{\tau} = \frac{\Delta \vec{L}}{\Delta t} \end{array} \right\}$$

$$\Delta t \rightarrow 0$$

$$\vec{\tau} = \frac{d\vec{L}}{dt}$$

$$\text{Si } \vec{\tau} = 0 \Rightarrow \underline{d\vec{L} = 0}$$

$$\vec{F} = \frac{d\vec{p}}{dt}$$

En absence de moment de force,
le moment cinétique est CONSERVÉ  

RECAP

Symétrie entre les lois de translation et celles de la rotation

$$\vec{F} = m \vec{a}$$

$$\vec{p} = m \vec{v}$$

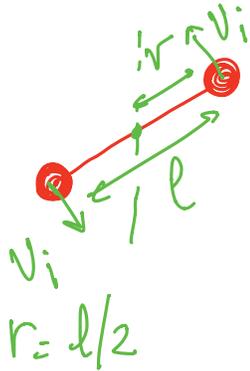
$$\vec{F} = \frac{d\vec{p}}{dt}$$

$$\vec{\tau} = I \vec{\alpha}$$

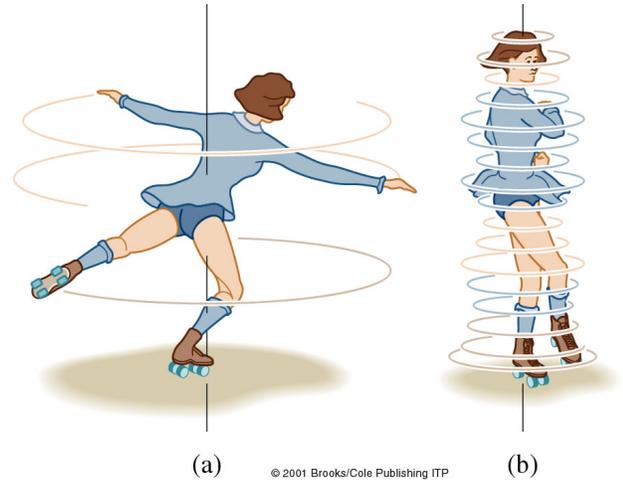
$$\vec{L} = I \vec{\omega}$$

$$\vec{\tau} = \frac{d\vec{L}}{dt}$$

EXAMPLE



$$l_i = 50 \text{ cm}$$
$$\omega_i = 2 \text{ rev/s}$$
$$l_f = 160 \text{ cm}$$
$$\omega_f = ?$$



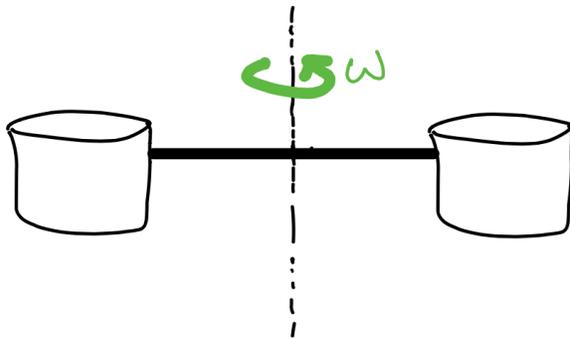
$$L_i = I_i \omega_i = 2m \cdot r_i^2 \cdot \omega_i$$

$$L_f = 2m r_f^2 \cdot \omega_f$$

$$L_i = L_f \Rightarrow r_i^2 \omega_i = r_f^2 \omega_f$$

$$\Rightarrow \omega_f = \frac{r_i^2 \omega_i}{r_f^2} \approx 0.2 \text{ rev/s}$$

QUESTION



$$L_i = 2m_i r^2 \omega_i$$

$$L_f = 2m_f r^2 \omega_f$$

$$L_i = L_f$$

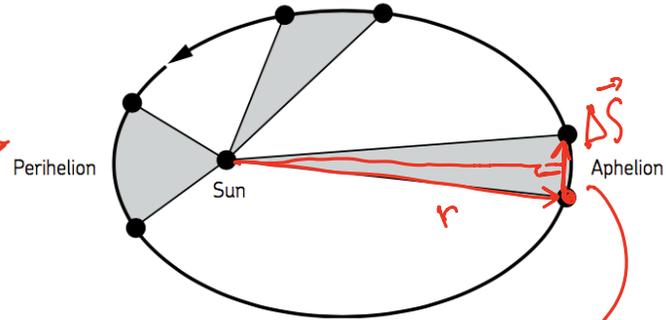
$$m_i \omega_i = m_f \cdot \omega_f$$

FLASH BACK: 2^{ÈME} LOI DE KEPLER

$$A = \frac{a \cdot b}{2}$$

$$\vec{L}_i = \vec{r} \times \vec{p} \Rightarrow L = r p \sin \theta$$

$$p = m v = m \frac{\Delta S}{\Delta t}$$



Orbit of a planet according to Kepler's Second Law

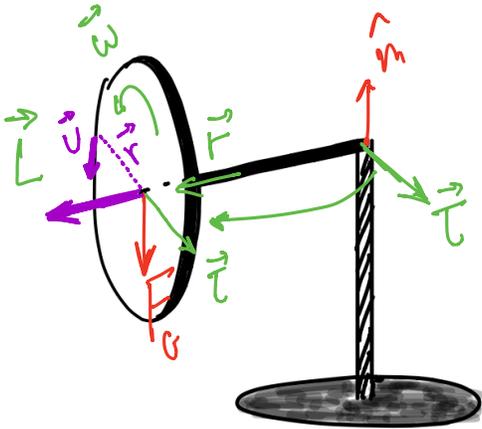
$$\vec{L}_f = \vec{L}_i = r m \frac{\Delta S}{\Delta t} \sin \theta \Rightarrow \Delta A = \frac{\Delta \vec{S} \cdot r \cdot \sin \theta}{2}$$

$$\Rightarrow r \cdot \Delta S \cdot \sin \theta = \text{const} \Rightarrow \underline{\underline{\Delta A = \text{const}}}$$

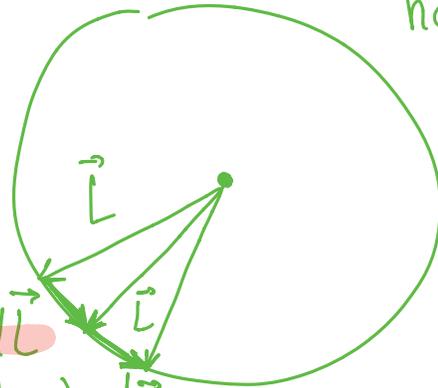
LE GYROSCOPE

$$\vec{F}_G \Rightarrow \vec{\tau} \Rightarrow$$

$$\vec{\tau} = \frac{d\vec{L}}{dt}$$



vue depuis le haut



(dans la direction de $\vec{\tau}$)

- c'est de $d\vec{L}$ qui maintient le mouvement